

Science and Technology "Chikyu" Expeditions

ECORD Industry Liaison Panel Meeting
Edinburgh, Scotland
11-12 June 2014

Nobu Eguchi





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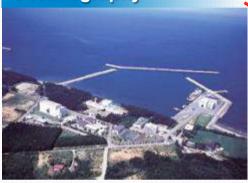
- JAMSTEC
- CDEX
- IODP
- "Chikyu"
- Expedition results
- Future projects



JAMSTEC Headquarters and Branches



Mutsu Institute for Oceanography



Tokyo Office



Yokohama Institute for Earth Sciences



Global Oceanographic Data Center



Kochi Core Center



Yokosuka Headquarters



Established in 1971



JAMSTEC Mission Vision for the next 15 years



An Integrated Understanding and Prediction of Global Environmental Changes

An Advanced Understanding of the Earth's Interior, and Mitigation of Earthquake and Tsunami Disasters





An Integrated Understanding of the Ocean, Earth, and Life

A Comprehensive Study of the Evolution of Life and the History of the Earth

A New Approach to Resources Research include Biological

JAMSTEC Executives, Personnel and Budget

Executives

President



Dr. Asahiko Taira

Auditor



Mr. Yasushi Taya



Dr. Yuko Maeda

Executive Director



Dr. Yoshihisa Shirayama



Dr. Hitoshi Hotta



Mr. Hisashi Dobashi

Total: 1,059 employees Scientists (351) Engineers (238) Crews (46) Support Staff (243) Administrative Staff (181) As of April 1, 2014

FY14 Budget

Total Budget: $\pm 38.0B$ (\$380M) (\$1= \mathrm{1}{2} 100)

(national treasury disbursement : ¥ 34.2B (\$342M)

JAMSTEC Outline



Japan Agency for Marine-Earth Science and Technology

Kochi Institute for Core Sample Research

Mutsu Institute for Oceanography Yokohama Institute for **Earth Sciences**

Headquarters







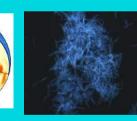
Research Sector

Basic Research Area

Strategic Research and Development Area







Research Support **Departments**

Kochi Institute for Core Sample Research (KOCHI)

Mutsu Institute for Oceanography (MIO)

and Operation **Development** Sector

Manned Submersible



Three Latest AUVs



Deep-sea Drilling Vessel



Earth Simulator



Basic Research Area



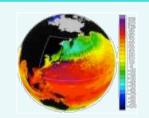
- Dept. of Coupled Ocean-Atmosphere-Land Processes Research
- Dept. of Environmental Geochemical Cycle Research
- Dept. of Integrated Climate Change Projection Research
- Dept. of Seamless Environmental Prediction Research
- Dept. of Deep Earth Structure and Dynamics Research
- Dept. of Solid Earth Geochemistry
- Dept. of Marine Biodiversity Research
- Dept. of Subsurface Geobiological Analysis and Research
- Dept. of Biogeochemistry
- Dept. of Mathematical Science and Advanced Technology
- Laboratory of Ocean-Earth Life Evolution Research



Strategic R&D Area



R&D	Center	for	Global
Char	ige		



R&D Center for Submarine Resources



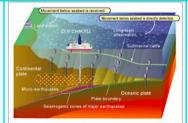
R&D Center for Ocean Drilling Science



Application Laboratory

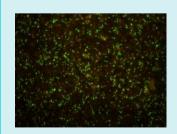


R&D Center for Earthquake and Tsunami



Project Team for Risk Information on Climate Change





Project Team for Analyses of Changes in East Japan Marine Ecosystems



Focused R&D Areas 2014-2018





Ocean and Global Climate
Change
Detect signals of global
environmental change













Vessels







Various observations with ROV

R/V YOKOSUKA



D/V CHIKYU



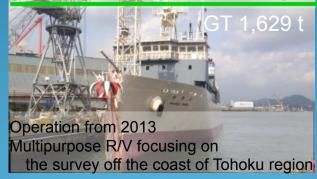
R/V KAIYO



R/V MIRAI



R/V SHINSEIMARU



R/V HAKUHOMARU



Multipurpose research vessel with long-term cruise

R/V KAIREI



Surveys the structure of sub-bottoms mainly with MCS

R/V (under planning)



Planned to be operated from 2016
Aims to survey for submarine resources 10



Manned/Unmanned Underwater Vehicles



Shinkai2000(Retired)



















ROV under construction





CDEX New Organization Chart

(after April 1st., 2014)





Director General (Kuramoto)



Senior Adviser (Yamao) For Operation Senior Adviser (Kobayashi)
For HSE and Contract



Planning & Coordination

Dpt.

(Kikuta)



Science Services Dpt. (Eguchi)



Engineering Dpt. (Kyo)



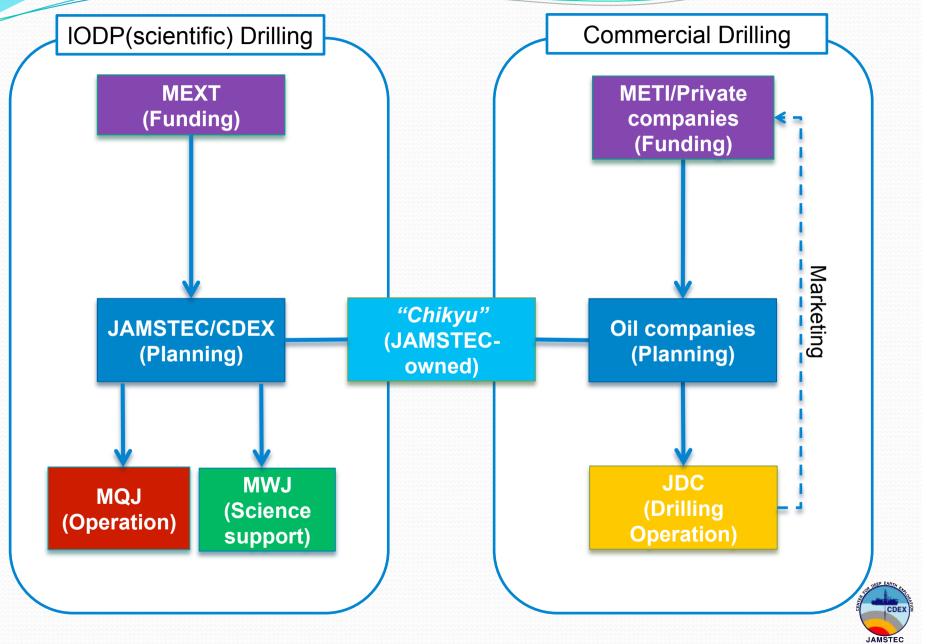
Operation Dpt. (Sawada)



HS E G.

"Chikyu" operation structure

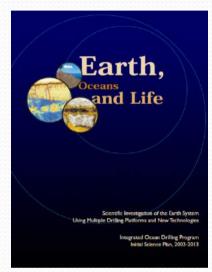


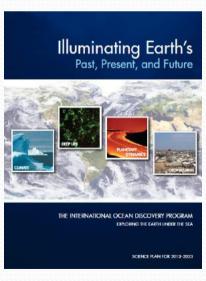


JAMSTEC

IODP Science Plans

- IODP: Integrated Ocean Drilling Program
 - FY2003 2013 (2004 2013)
 - Initial Science Plan: "Earth, Oceans and Life"
 - Scientific Investigation of the Earth System Using Multiple Drilling Platforms and New Technologies
- IODP: International Ocean Discovery Program
 - FY2013 2023 (2014 2023)
 - Science Plan: "Illuminating Earth's Past, Present and Future"
 - Exploring the Earth under the Sea







IODP Framework



IODP Forum

Custodian of the IODP Science Plan

Chikyu IODP Board

Members

MEXT

JAMSTEC/CDEX

(Chikyu operations & science service delivery)

JR Facility Board

Members

NSF

JR operator

(JR operations & science service delivery)

ECORD Facility Board

Members

ECORD/EMA

ESO

(MSP operations & science service delivery)

Advisory Panels(SEP, EPSP)

Support Office

proposal handling and other logistics

Proponents/Researchers





Facts & FAQ

- Chikyu funding situation for IODP:
 - MEXT provides 80MUSD/year
 - In new IODP, Chikyu program member contribution
 - Regular member: 1MUSD/year (EOCRD is a member)
 - Partnership member: 300K/year (ANZIC)
 - Project member: over 10MUSD/project
 - CPP (Complementally Project Proposal): 70% of total operation cost



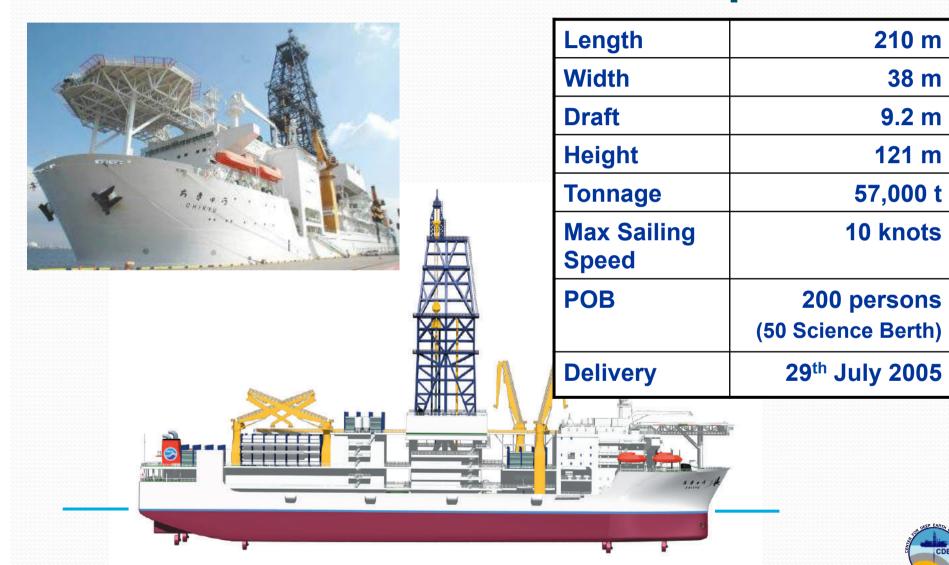


Facts & FAQ cont.

- Chikyu Cost:
 - For IODP & Research operation:
 - Transition: mobilization/demobilization: 300KUSD/day
 - Riser Drilling operation: 600~650KUSD/day (include planning & all services)
 - Riserless Drilling operation: 400KUSD/day (include planning & all services)
 - For Commercial Operation (Oil & Gus Business):
 - Marketing price: charter cost (500K/day include company profit)



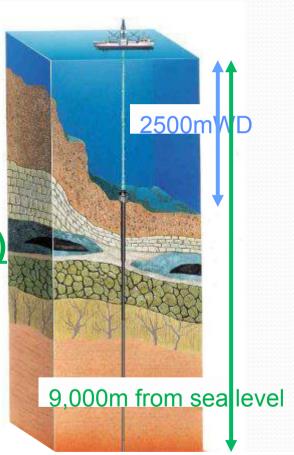
Scientific Drilling Vessel "Chikyu" 5th Generation Drill Ship





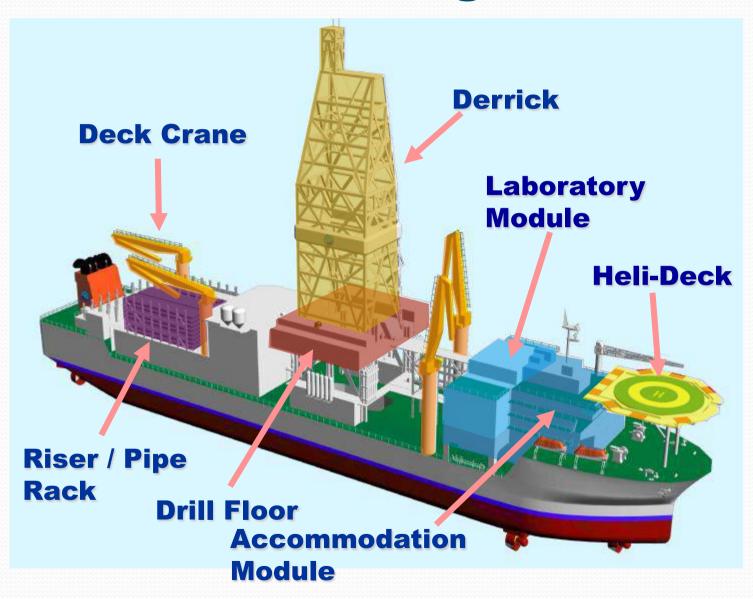
JAMSTEC

- Water Depth (Riser Operation)
 - Riser Drilling Max Water Depth (2500mWD)
 - Deepest Riser Drilling:
 - Kenya 2200mWD
- Total Depth (WD + Penetration Depth)
 - Max depth 9,000m from sea level
 - Deepest Riserless Drilling:
 - JFAST Expedition / 6897.5mWD (TD 7780.81mBRT)



General Arrangement







Lab Highlights



High performance facilities and staffs

- Physical properties: 12 (X-ray CT, etc)
- Paleomagnetics: 3 (SQUID, etc)
- Petrology/Paleontology: 8 (SEM-EDS)
- Geochemistry: 12 (ICP-MS, etc)







Additional Container labs

- Iso-van: controlled microbiology lab
- Mud-gas monitoring Lab

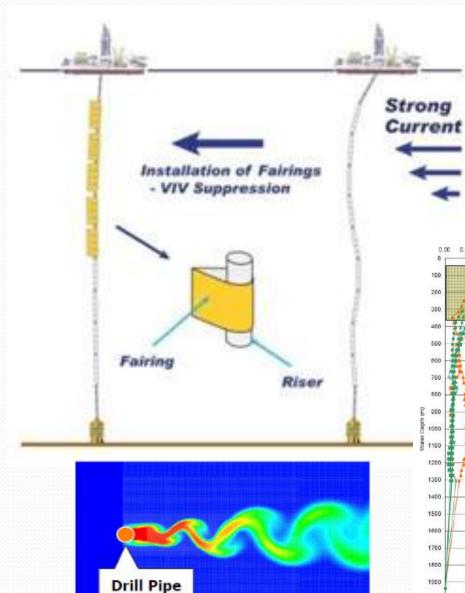






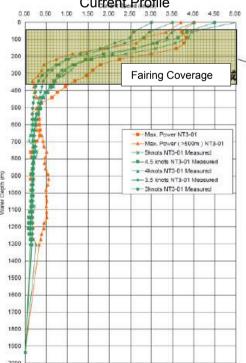


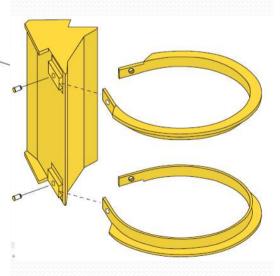
Riser Fairing



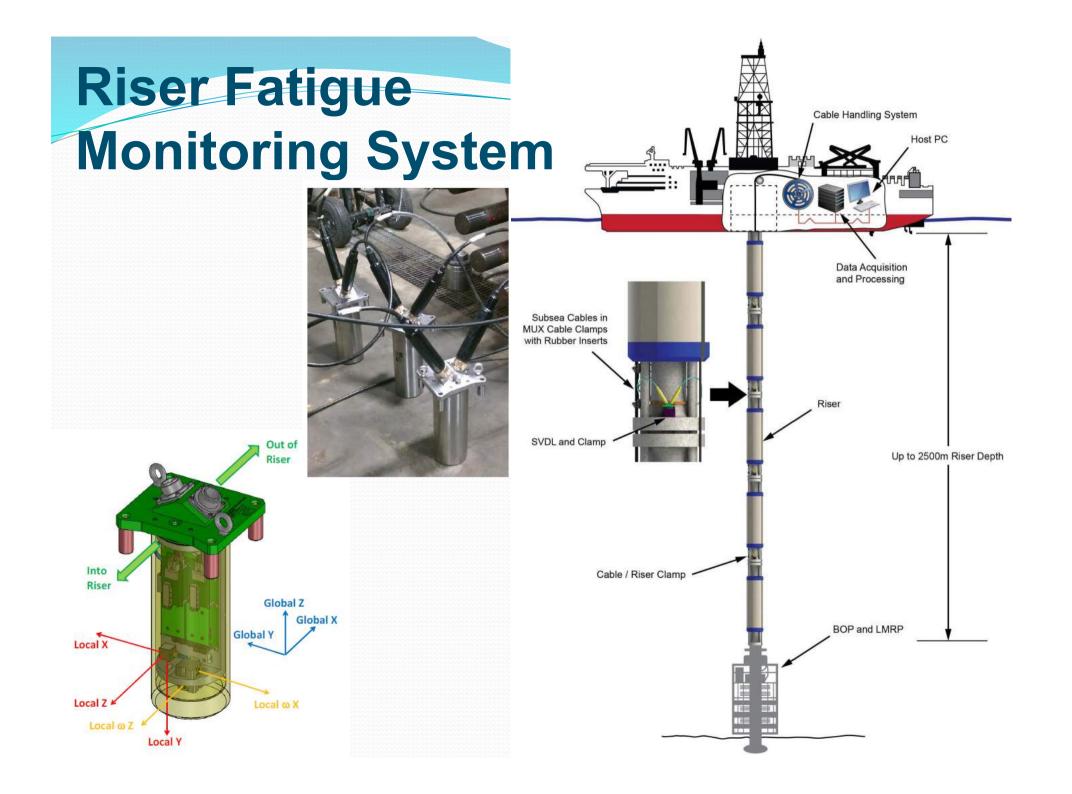








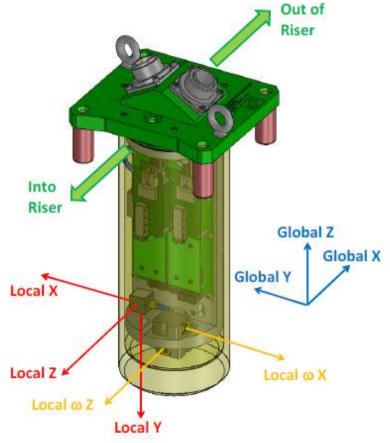




Riser Fatigue Monitoring System

Specification	Value	
Number of measurement modules (SVDL: Subsea Vibration Data Logger)	7 sets (possible to increase modules)	
Deployment Depth	2,500 meters (possible to extend to 4,000 m)	
SVDL Accelerometer range	± 2.0 g (triaxial)	
SVDL Accelerometer resolution	350 µg	
SVDL Angular Rate Sensor range	± 16 degrees/sec	
SVDL Angular Rate Resolution	0.0038 degrees/sec (5 Hz bandwidth)	





IAMSTEC

Riser Fatigue Monitoring System

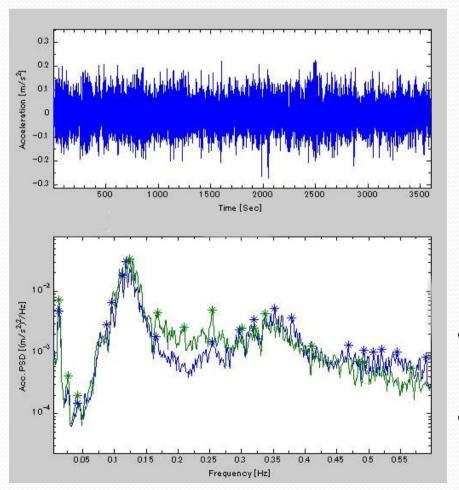


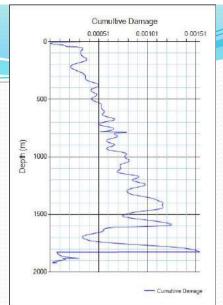


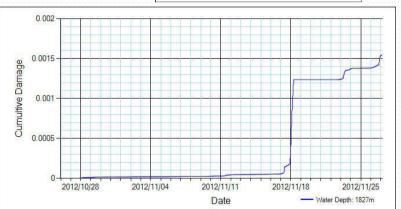




Riser Fatigue Monitoring System High Current Studies Results







- Suppress VIV at high Kuroshio current (with fairing)
- Cumulative Damage < 0.0015



Subsea Equipment







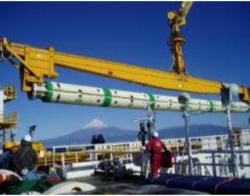
4,000m Class Riser System



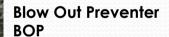
Vessel Modification
(Considering Riser storage and stability)

New Material Riser

- Carbon Fiber
- Aluminum Alloy
- Titanium Alloy
- Combination (steel + new material)







Riser



Compact BOP



Chikyu Existing Coring System (61mm core / wireline retrieval through DP) 11-7/16"Bit / Interchangeable 10-5/8"Bit Very Soft - Soft Moderate Soft - Hard Moderate - Hard Soft - Moderate **ESCS Hybrid PCS HPCS EPCS** RCB 51mm Core DE FISHING NECK HEAD SUB MER SHEAR PIN HEAD SUR NG SHOULDER SUB LANDING SEXT INSERT MATERIAL PROPERTY. SHEAR PINS Putting Tools (Modified PTCS) LATCH SLEEVE NINER SEALS ESCELATOH Ioner Table Later TOP SUB LATON ASSESSED T WITTER SEALS INNER BARROL SWIVEL ASSEMB ENCS COMPTEDION SPTING Built Valve Latch Scaled down from Seated Dearing MAIN COMPRESSION SPRING (Scaled down from INDIANOS COMPRESSOR LENGTH AGUSTER Albert Mary band FACR LICK RELEASE Buil Valve Sonno ERCS.ADAPTERS Province Recorded (Signed down from PTCS) OUTSE MATES. ---ER CORE BARRE. QUICK RELEASE ACTIFMENT RCB SWAIA, BEARING Scaled down from PISTON ROOS PTCS DIEDEVALVE DOTELL DAVIDE ACID STEED (Standard ESCS) DUCK FELLING ACCOME. inter Time Pico CORE LINER (From HPTC) **CUITER SARRES** Press/Tierre Baccette From PTCS3 NU NUM INNER TURE Butyrote Core Liner ASSEMBLY REQUORESKE-Non-insurated Inner Tube BIT SUB CORE LINER VER CORE TUBE CORE: COSE LINER-CORFINE STON ROO SNUBBER Low End Drive the this tests -LOWBDORNE - Elloot Volve FLOAT VALVE FLOAT VALVE INCT LINED FOR IPPOS PLOAT VALUE-PLOAT VALVE-OWER REAGING PISTON HEAD Top Sepi Ball Valve BIT SEAL BT SEAL CORE CATCHERS COME INT RE CATCHERS CORE BIT опаснянского Figure 11, Proposed Hybrid PCS **Hydraulic Piston Extended Punch Hybrid Pressure Extended Shoe Coring System Coring System Coring System Coring System Rotary Core Barrel**

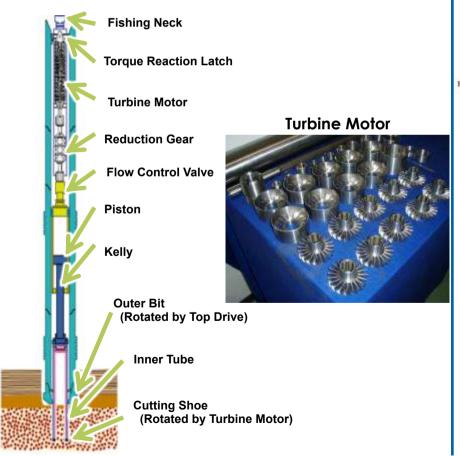
New Coring System

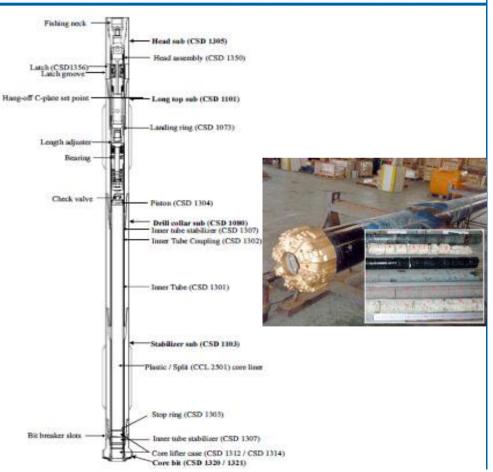
Turbine Driven Coring System (TDCS)

- o Trial in 2013
- o Compatible with HPCS/ESCS Core Barrel
- o High RPM Cutting Shoe: 1200rpm
- Hydraulic extending shoe

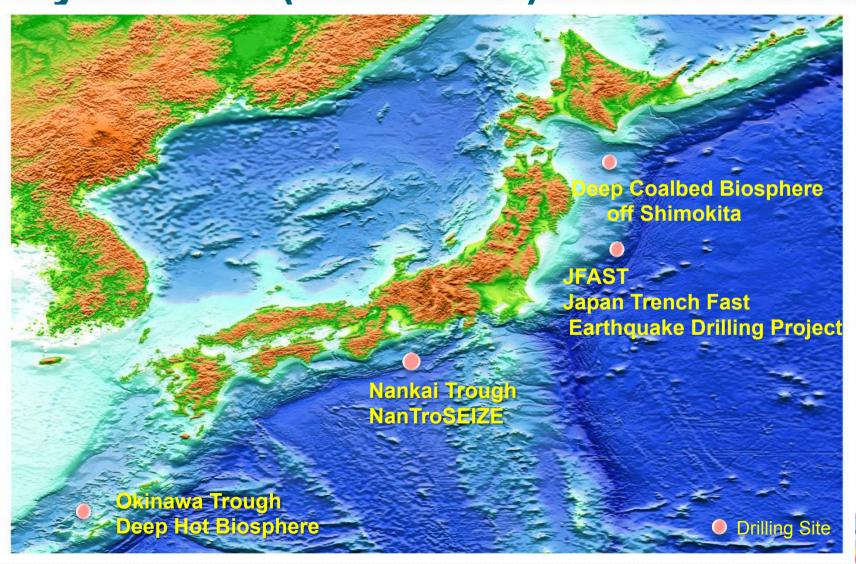
Small Diameter RCB (SD-RCB)

- Trial in 2013
- 2nd Generation RCB
- Slim Hole: 10-5/8" bit → 8-1/2" bit
- High Durability: 21kNm → 42kNm
- Large Core: 61mm → 75mm





"Chikyu" IODP Scientific Expeditions Key Results (2007-2013)

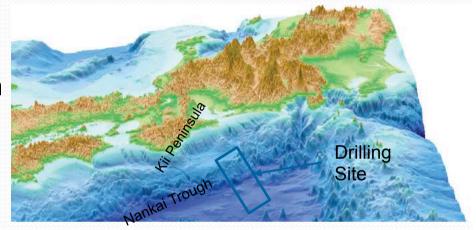


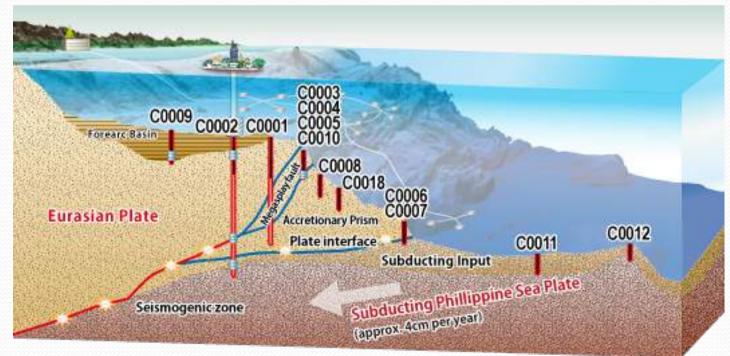
NanTroSEIZE

IAMSTEC

The Nankai Trough Seismogenic Zone Experiment

- Research Objectives
 Investigate the mechanism of earthquake occurring at Subduction Zone
- Drilling Site
 Nankai Trough, Off Kii Peninsula,
 Japan





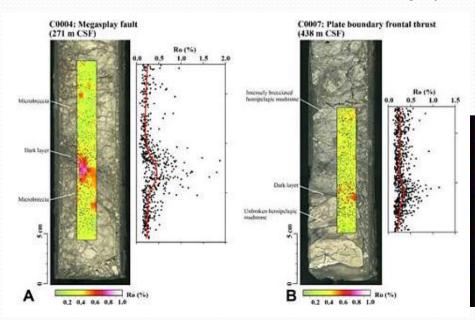


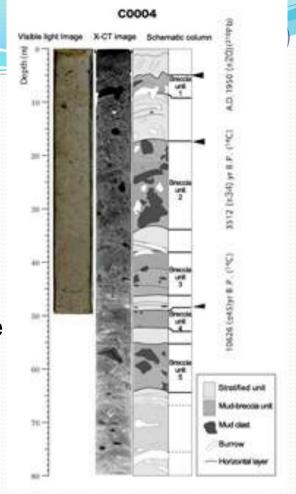
NanTroSEIZE



Achievements and Findings

- "Big picture" of the Nankai Trough
- Origin and evolution of a splay fault
- Mud brecciation due to the past great earthquake
- Evidence of Tsunami generating seismic rupture
- Successful riserless observatory (LTBMS)









Deep Hot Biosphere



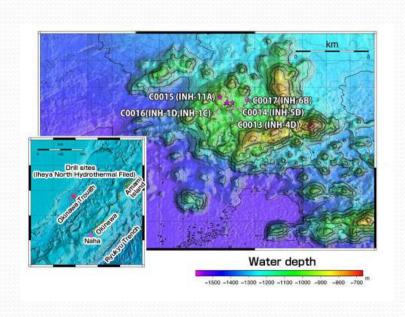


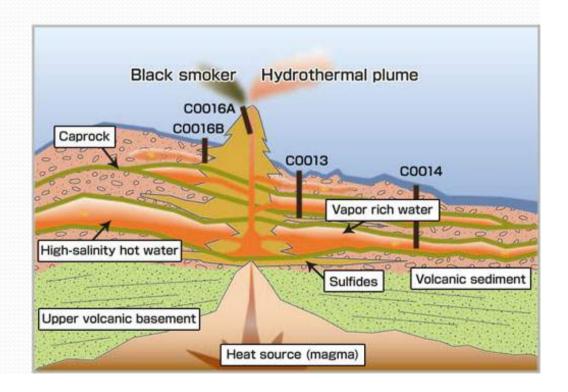
Research Objectives

Prove the existence of microbial communities, their biomass and ecosystem roles and functions

Drilling Site

Okinawa Trough, Iheya North hydrothermal field, Japan





Deep Hot Biosphere

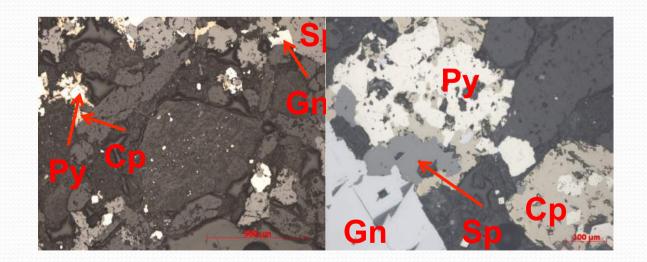






Achievements and Findings

- Subseafloor hydrothermal alteration, fluid flow, and reservoirs within the defined hydrogeologic structure
- Stratification of hydrothermal fluid by subseafloor phase separation and segregation



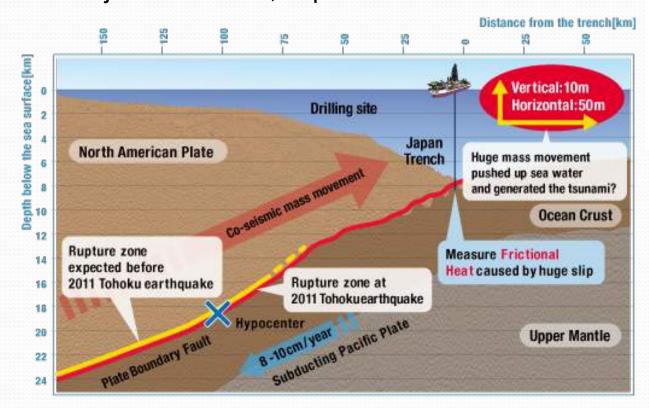


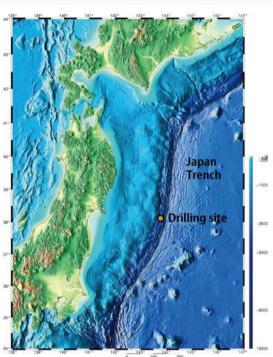




Japan Trench Fast Earthquake Drilling Project

- Research Objectives
 Analyze the frictional properties of the plate boundary fault at 2011 Tohoku earthquake
- Drilling Site
 Off Ojika Peninsula, Japan











Japan Trench Fast Earthquake Drilling Project

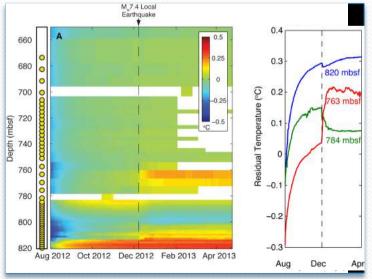
Achievements and Findings

- Identified fault zones at two intervals
- Highly sheared clay samples from plate boundary décollement (evidence of slip)
- 55 temperature sensors (MTL) installed across the two fault targets and retrieved after 9 months, and the data successfully acquired











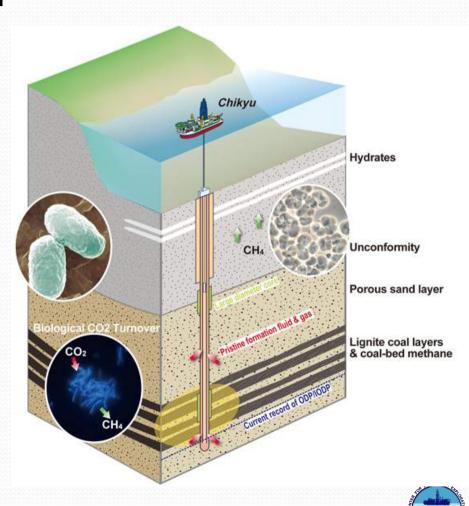
Deep Coalbed Biosphere off Shimokita

Research Objectives

Clarify deep underground biological activity, an important role in the system of carbon cycling below the sea floor.

Drilling Site
 Off Hachinohe, Japan



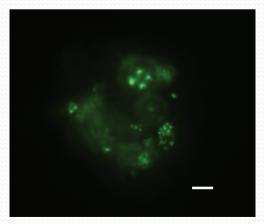


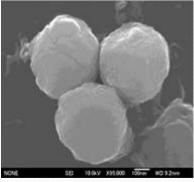
Deep Coalbed Biosphere off Shimokita

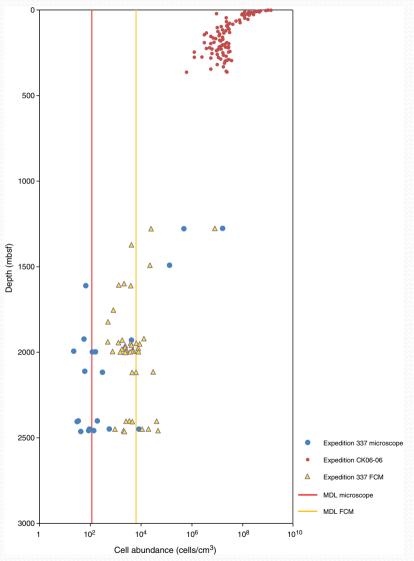


Achievements and Findings

- Evidence for deep subseafloor microbial activity associated with coalbeds
- Interactions between a deep coalbed hydrocarbon system and subseafloor life.



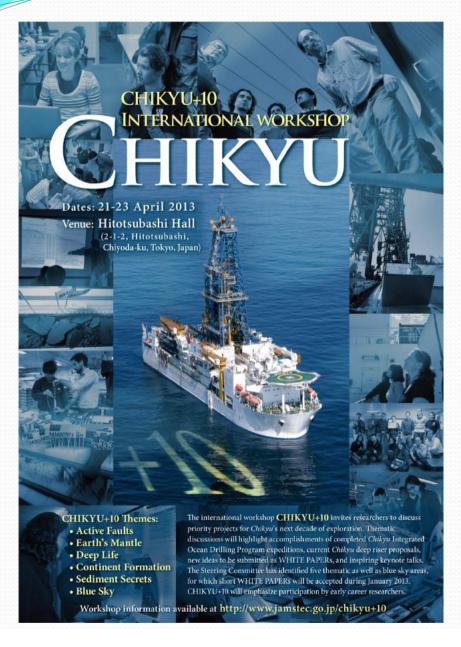






CHIKYU +10 International WS





Objective:

To discuss priority projects for *Chikyu*'s next decade of exploration in the below 5 themes;

- 1. Active Faults
- 2. Earth's Mantle
- 3. Deep Life
- 4. Continent Formation
- 5. Sediment Secrets



CHIKYU +10 International WS cont.

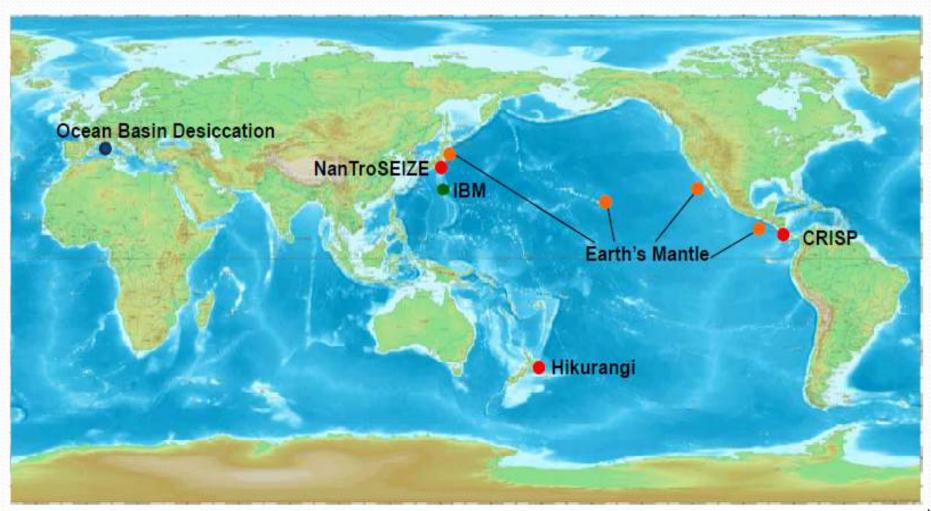
• Flagship Projects:

- The Dynamic Fault Behavior
 - Nankai Trough Seismogenic Zone Experiment (NanTroSEIZE)
 - Costa Rica Seismogenesis Project (CRISP)
 - Slow Slip at the Hikurangi Margin
- The Ocean Crust and Earth's Mantle
 - Drilling to Earth's Mantle (M2M)
 - Life Cycle of the Oceanic Lithosphere
- The Deep Life and Hydrothermal System
 - Habitable Zone
- The Continent Formation
 - Island arc Origin: Izu-Bonin-Mariana (IBM)
- The Sediment Secrets
 - Ocean Basin Desiccation





Proposed Sites Map







Projects Overview

	NanTroSEIZE	CRISP	Hikurangi	Earth's Mantle	Oceanic Lithosphere	Habitable Zone	IBM	Ocean Basin Desiccation
Theme	Dynamic Fault	Dynamic Fault	Dynamic Fault	Earth's Mantle	Earth's Mantle	Deep Life	Continent Formation	Sediment Secrets
Location (LA, LO)	33.3°N 136.6°E	9.5°N 84°W	38.73°S 178.61°E	Cocos PlateHawaiiBaja Califomia	Cocos Plate Japan Trench		32.4°N 140.4°E	41.76°N 5°E
Water Depth (m)	2,000	500	1,000	~4,000	>4,000		1,800	>2,500
Drilling Depth (mbsf)	~5,000	~5,000	>5,000	>6,000	~6,000		~5,500	~6,000
Technical Challenge	Deformed over-press. sediments High current Typhoon Observatory	Deformed over-press. sediments Observatory	Deformed over-press. sediments Observatory.	Hard rock: Lava Dikes Gabbro Mantle BHT 150-250°C Observatory	Hard rock Fault zone	• BHT >300°C	Hard rock: Andesitic Tonalite Diorite BHT 150-175°C Observatory	Salt formation Over-press.



Sponsoring / Project Support

- Opportunities?
 - Donations
 - In-kind Contribution
 - Sponsoring
 - JAMSTEC/CDEX
 - Chikyu
 - Project
 - Partnership
 - Research Collaborations (e.g., Horizon 2020)
 - Industry operation in the area?
 - Others







*"Chikyu"*Scientific Drilling Vessel 5th Generation Drill Ship



OWNER and BUILD	DER	ClassNK		
Owner	JAMSTEC	 NS*: Mobile Offshore Drilling Unit DPS Class B Ice Strengthening Class IB MNS*: (M0) 		
Built Year	2005			
Builder	MHI/MES			
MAIN DIMENTIONS		COMPLEMENT		
Length overall	210.0 m	Max.	200 persons	
Breadth overall	38.0 m			
Depth	16.2 m	Fuel oil	9,006 m ³	
Operational draft	9.2 m	Drill water	2,554 m³	
Gross Tonnage	56,752 tons	Potable water	369 m³	
Helicopter deck	Capable for EH101	Active mud	408 m³	
DESIGN CRITERIA		Reserve mud	1,445 m³	
Cruising speed	11.45 knots with 5 thrusters	Bulk mud	696 m³	
Max. operating	unusiers	Bulk cement	464 m³	
water depth	2,500m	VARIABLE LOAD		
Max. drill string length	10,000m		25,500 tons	

POWER EQUIP.	MODEL/SPEC	MANUFACTURER
Main	<12ADD30V>×6 • 5,270 kW (7,064 HP) x 720 rpm	Mitsui
generator	 5,000 kW (6,250 kVA), AC 6.6 kV, 60 Hz, 3 phase 	Nishishiba
Aux generator	⟨6ADD30V⟩×2 2,640 kW (3,539 HP) x 720 rpm 	Mitsui
	 2,500 kW (3,125 kVA), AC 6.6 kV, 60 Hz, 3 phase 	Nishishiba
Emergency generator	⟨S12A2-MPTA⟩×1 560 kW (700 kVA), AC 450 V, 60 Hz, 3 phase 	Mitsubishi
MATERIAL HANDLING EQUIP.	MODEL/SPEC	MANUFACTURER
Deak arana	〈ElectHyd. Knuckle Boom Crane C3426KE-45/15x35-1.33 >×2 Capacity 45 ton	NOV
Deck crane	〈ElectHyd. Knuckle Boom Crane C3932KE-85/20x42-1.33 >×2 Capacity 85 ton	NOV
BOP crane	• SWL 200 ton ×2	NOV

DRILLING EQUIP.	MODEL/SPEC	MANUFACTURER
Derrick	 ⟨Dual Well Type Bolted Dynamic Derrick⟩ 21.95 m (72ft) L x 18.29 m (60ft) W x 70.10 m (230ft) H Well center spacing 9.75 m (32") Max. static hook load 1,250 ton 	Bailey
Crown Mounted Heave Compensator	 CMC1000-25 with AHC> Hook load capacity: 518 ton (1,140 kips) Crown Block capacity: hook load 1,250 ton Stroke 7.62 m (25 ft) 	NOV
Traveling Block	⟨HTB1380⟩×8• 1981 mm (78") dia.• Capacity 1,250 ton	NOV
Drilling Control System (DCIS)	⟨Cyberbase Control System⟩	NOV
Drawworks	 ⟨EH-V-5000⟩ Hoisting capacity 1,250 ton Drum Size: 1,448 mm (57") dia. x 3,683 mm (145") length ⟨GE 752RB1 Marine Shunt Wound Drilling Motor⟩×4 4 x 930 kW, Total 5,000 HP 	NOV
Drill Lines	 ⟨6 x 26 WS IWRC⟩ • Max. 3,048 m (10,000 ft) - 54 mm (2-1/8") • B.L. 2,277 kN (223 ton) 	TESAC

DRILLING EQUIP. (cont'd)	MODEL/SPEC	MANUFACTURER
Rotary table	⟨RST 60-1/2⟩ (Main well) Static capacity 1,250 ton ⟨RST 49-1/2⟩ (Aux. hole) Static capacity 750 ton 	NOV
Power Swivel	 ⟨HPS 1000 2E AC⟩×2 858 kW (1,150 HP) GEB AC Eex eII Max. 260 rpm Hoisting capacity 1,000 s.ton 	NOV
Tensioner system	 ⟨N-Line Direct Cylinder Tensioner⟩×6 • Tensioner Cylinder 363 ton (800 kips) • Stroke 52ft 	NOV



BULK and MUD SYSTEMS	MODEL/SPEC	MANUFACTURER
Bulk handling system	 Barite 4,400~5,000 lbs/min. (120~218 ton/h) Cement 3,850~4,000 lbs/min. (105~109 ton/h) 	Halliburton
	〈Mud Mixing System〉	NOV (Procon)
	〈Active Mud Tank, Vertical Cylindrical Tank〉 85 m³×6 	Henmi
Mud mixing and storage system	 (Mud Agitator, MA-25) 25 HP 3.63 m Shaft, 2 x 1.02 m (40") Impeller Blade Speed 58 rpm, TOR 68.6 sec. 	Brandt
	⟨Reserve Mud Tank, Vertical Cylindrical Tank⟩ 212.5 m³×8 	Henmi
Mud supply system	⟨Mud pump,14-P-220⟩×3	NOV
	⟨Gumbo separator, 6 ft Single Cartridge Gumbo Scalper⟩×2	Brandt
	⟨Shale shaker, VSM300 Elliptical Cascade Shaker⟩×6	Rigtech
Mud solid control	⟨Degasser, Magna-Vac Model 1500⟩×2	Burgess
system	⟨Desander, 3-12 D-Sander⟩×2	MiSWACO
	⟨Mud clearner, 8T4/ALS II D-Silter/Adjustable Linear Shaker⟩×2	MiSWACO
	⟨Centrifuge, RT HeviJet 362⟩×3	HILLER

WELL CONTROL Cont'd	MODEL/SPEC	MANUFACTURER
BOP Stack	 \(18-3/4" 15M Stack, with Vetco Gray SHD Wellhead Connector, Pods & Shaffer Dual Annular \) \(5,232 mm (206") L x 5,918 mm (233") W x 14,513 mm (571.38") OAH \) \(LMRP \) \(Lower Flex Joint, Oilstates 18-3/4", 1,588 ton (3,500 kips) Working Tension, +/- 10° \) \(Dual Annular, Shaffer Spherical BOP x 2, 18-3/4" 10K \) \(Lower Stack \) \(Cameron Double Ram, 18-3/4" 15K TL \) \(Cameron Triple Ram, 18-3/4" 15K TL \) 	Cameron
BOP control system	Mux Control System	Axon
Diverter system	⟨KFDS/CSO⟩ 21"bore, 35 bar (500 psi) WP	Vetco Gray
Riser System	 Main tube 〈LoadKing 4.0〉 19.5"ID x 90 ft, 1,814 ton (4,000 kips) Choke/Kill 〈ASTM A-519 Gr.4130〉×2 6.25"OD/4.25"ID, 103.4 MPa (15,000 psi) Booster 〈ASTM A-519 Gr.4130〉 5"OD/4"ID, 51.7 MPa (7,500 psi) Hydraulic 〈UNS S31803〉 3.625"OD/3"ID, 34.5 MPa (5,000 psi) 	Cameron

WELL CONTROL Cont'd	MODEL/SPEC	MANUFACTURER
Choke and Kill	 Choke/Kill Manifold> 3-1/16" 15,000 psi (Hyd. and Manual Choke) 4-1/16" 5,000 psi (Hyd. and Manual Choke) 	Cameron
System	 (Mud Gas Separator) 1.829 m (6ft) dia. x 14.191 m OAH 566 Mm3/day (20 mmcf/day) = 6.55 Nm3/s 	MisWACO



PIPE HANDLING	MODEL/SPEC	MANUFACTURER
D. D. I.	 〈Hydra Racker IV, Hydraulic Trolley Column with 3 Arms〉 Hoisting Capacity: Main Arm 12.5/6.75/4 ton @ 2.7/3.6/3.9 m reach 	NOV
Pipe Racking System	⟨Fingerboard / Bellyboard⟩84 x 13-3/8"CSG + 324 x 6-5/8"DP + 20 x 8"DC + 20 x 9-3/4"DC	
	⟨Racking Winch for Fingerboard / Bellyboard⟩1T Utility Winch, SWL: 10 kN	NOV (Bryne Mekanikk)
	⟨Hyd. Roughneck HRN-166⟩ Pipe Range: 3-1/2" to 9-3/4 ⟨KT14000/25000 casset type tong⟩ Range 4-1/2"~25" 	NOV
Drill Floor Pipe	(Hydraulic Manipulator Arm)Pipe Sizes: 3-1/2" to 60" (Range of heads required)	Patriot
Handling Equipment	(Pipe Transfer System (Hyd. Operated Catwalk Machine))3-1/2" to 30" pipe, SWL 20 ton	NOV
	(Riser Transfer System (Hyd. Operated Catwalk Machine))90 ft Riser & Slip Joint, SWL 45 ton	NOV
Elevators	⟨Dual Elevator System⟩Load capacity: 750 s. tonPipe Dia. Range: 2-3/8" to 9-5/8"	Blohm+Voss DES

DRILL STRING EQUIP.	MODEL/SPEC	MANUFACTURER
Drill Pipe	 ⟨5" Drill Pipe⟩ • 5"OD, S-140, 19.5lbs, 5-1/2"FH DSTJ, R-2 ⟨5-1/2" Drill Pipe⟩ • 5-1/2"OD, S-140, 24.7lbs, 5-1/2"FH DSTJ • 5-1/2"OD x 0.506"t, S-150, 5-3/4"FH DSTJ, R-2 ⟨6-5/8" Drill Pipe⟩ • 6-5/8"OD, Z-140, 47.06lbs, 6-5/8"FH, R-2 (Scientific project use) 	NKK Grant
CORING EQUIP.	MODEL/SPEC	MANUFACTURER
Coreline Winch	⟨Dual Drum, Chain drive Elect. Winch⟩ Capacity 19 mm (3/4") Wire Rope x 10,000 m (33,000ft) 	NOV
Core Line	 19 mm (3/4") 6 x WS(36) OF (Omega Filler) IWRC x 10,000 m, B.L. 309 kN (31.5 ton) 19 mm (3/4") 4 x F(40) G/S (Single Rope) x 10,000 m, B.L. 301 kN (30.7 ton) 	TESAC
Core Carrier	 ⟨Hydraulic on Fwd Catwalk⟩ 200 mmW x abt. 24 mL Traveling Load/Length/Speed 0.5 kN/17.95 m/0~60 m/min. 	Nishiatsu Engineering